

Optical reading head PGV100-F200-R4-V19

- Mechanically rugged: no wearing parts, long operating life, maintenance-free
- RS-485 interface
- Non-contact positioning on Data Matrix code tape
- Noncontact positioning with Data Matrix TAGs
- Noncontact lane tracking of a colored strip
- Reading of Data Matrix control codes
- White-blue light

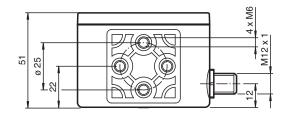
Read head for incident light positioning system

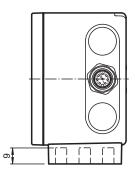


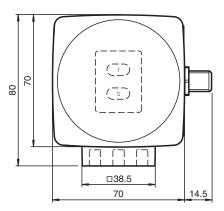




Dimensions







Technical Data

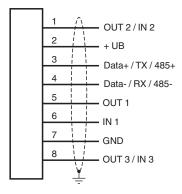
General specifications				
Passage speed	V	≤ 8 m/s		
Measuring range		max. 10000 m		
Light type		Integrated LED lightning (white/blue)		
Scan rate		25 s ⁻¹		
Latency		60 ms		
Read distance		100 mm		
Depth of focus		± 20 mm		
Reading field		120 mm x 80 mm		
Ambient light limit		100000 Lux		
Accuracy		± 0.2 mm		
Nominal ratings				

Technical Data		
Camera		
Туре		CMOS , Global shutter
Processor		,
Clock pulse frequency		600 MHz
Speed of computation		4800 MIPS
Digital resolution		32 Bit
Functional safety related parameters		
MTTF _d		89 a
Mission Time (T _M)		10 a
Diagnostic Coverage (DC)		0%
Indicators/operating means		
LED indication		7 LEDs (communication, alignment aid, status information)
Electrical specifications		(communication, anglimoni and, ciando micrimans)
Operating voltage	U_B	15 30 V DC , PELV
No-load supply current	I ₀	max. 200 mA
Power consumption	P ₀	3 W
Interface	. 0	
Interface type		RS 485 interface
Data output code		binary code
Transfer rate		38400 230400 Bit/s
Termination		Switchable terminal resistor
		≥ 10 ms
Query cycle time		2 10 1115
Input		1 to 0 functional inputs and are madels
Input type		1 to 3 functional inputs , programmable ≥ 27 kΩ
Input impedance		2 2 / K1
Output		1 to 2 quitab quanta DND programmable, about airquit protected
Output type		1 to 3 switch outputs , PNP , programmable , short-circuit protected
Switching voltage		Operating voltage
Switching current		150 mA each output
Conformity		EN 00000 0 07 0000
Shock resistance		EN 60068-2-27:2009
Vibration resistance		EN 60068-2-6:2008
Emitted interference		EN 61000-6-4:2007+A1:2011
Noise immunity		EN 61326-1:2013
Photobiological safety		Risk group 1 according to EN 62471:2008
Approvals and certificates		
CE conformity		CE
UL approval		cULus Listed, Class 2 Power Source, Type 1 enclosure
CCC approval		CCC approval / marking not required for products rated ≤36 V
Ambient conditions		
Operating temperature		$0 \dots 60~^{\circ}\text{C}$ (32 \dots 140 $^{\circ}\text{F})~,~$ -20 \dots 60 $^{\circ}\text{C}$ (-4 \dots 140 $^{\circ}\text{F})$ (noncondensing; prevent icing on the lens!)
Storage temperature		-20 85 °C (-4 185 °F)
Relative humidity		90 % , noncondensing
Mechanical specifications		
Connection type		8-pin, M12 x 1 connector
Degree of protection		IP67
Material		
Housing		PC/ABS
Mass		approx. 160 g
Dimensions		
Height		70 mm
Width		70 mm

_			_		
100	nn	cal		-	та
		199		4-1	1401

Depth	50 mm
Factory settings	
X resolution (protocol)	0.1 mm
Y resolution (protocol)	0.1 mm
Speed resolution (protocol)	0.1 m/s
Angle resolution	0.1 °
Baud rate	115200 Bit/s
Extrapolation	On
Read head address	0

Connection

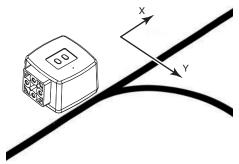


Connection Assignment

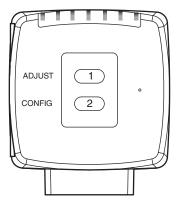


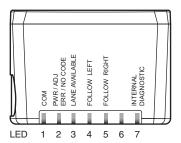
Characteristic Curve

Coordinates



Characteristic Curve





4

General

The PGV... reader forms part of the positioning system in the Pepperl+Fuchs incident light process. The reader's features include a camera module and an integrated illumination unit. The reader uses these features to detect a colored strip stuck to the floor to track the lane. The reader also detects control codes and position markers in the form of Data Matrix codes attached to a self-adhesive code tape. The code tape is usually mounted in a fixed position instead of the colored strip or parallel to the colored strip. The reader is located on the front of an automated guided vehicle and guides this vehicle along the colored strip.

Mounting and Commissioning

Additional Information

Mount the reader such that the optical surface of the device captures the optimum reading distance to the colored strip (see "Technical Data"). The stability of the mounting and the manner in which the vehicle is guided ensure that the reader is not operated outside of its depth of focus range. The colored strip must not leave the maximum reading window for the reader during this process.

All readers can be adapted to optimally meet specific requirements by means of parameterization.

Indicators and Operating Controls

The PGV... reader is equipped with seven indicator LEDs for carrying out visual function checks and rapid diagnostics. The reader is equipped with two buttons at the back for activating the alignment aid and parameterization mode.

LEDs

LED	Color	Label	Meaning
1	Yellow	COM	Communication active
2	Green/red	PWR ERR/NO CODE	Code detected/not detected, error
3	Yellow	LANE AVAILABLE	Lane available
4	Yellow	FOLLOW LEFT	"Follow left-hand lane" activated
5	Yellow	FOLLOW RIGHT	"Follow right-hand lane" activated
6	Red/green/yello	INTERNAL	Internal diagnostics
7	w	DIAGNOSTIC	

External Parameterization

In order to parameterize the device externally, the parameterization code is required in the form of a Data Matrix containing the desired reader parameters. Data Matrix code cards detailing the step-by-step process for externally parameterizing the device are printed in the operating instructions for the reader.

The reader can be parameterized only within ten minutes of being switched on. If a key is pressed after ten minutes of the device being switched on, a visual signal is given by the LEDs (LED1, yellow/LED2, red/LED3, yellow/LED4, yellow/LED5, yellow, flashing for two seconds).

- The switchover from normal mode to parameterization mode is made by pressing button 2 on the back of the reader. To switch the device
 over, button 2 must be pressed and held for more than two seconds. LED3 then flashes.
 - **Note:** Parameterization mode is exited automatically if the device is inactive for one minute. In this case, the reader reverts to normal mode and operates without the settings having been changed.
- Place the parameterization code in the field of vision of the camera module. After the parameterization code is detected, the green LED2 lights
 up for one second. In the event of an invalid parameterization code, LED2 lights up red for two seconds.
- Briefly pressing button 2 will end parameterization mode.